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# Common Fixed Point for Compatible Mappings of Type (α) Satisfying an Implicit Relation

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#### **Abstract**

Here we prove a common fixed point theorem for compatible mappings of type ( $\alpha$ ) satisfying an implicit relation. We extend results of Popa [9] for five mappings.

Keywords: Implicit relation, compatible mappings, complete metric space, fixed point

#### 1. INTRODUCTION

In 1976, Jungck [3] proved a common fixed point theorem for commuting mappings generalizing the Banach's fixed point theorem. Sessa [10] defined a generalization of commutativity, which is called weak commutativity. Further Jungck [4] introduced a more generalized notion of commutativity, the so called compatibility, which has a more general character than that of the weak commutativity. The utility of compatibility in the context of fixed point theory was demonstrated by extending a theorem of Park and Bae [8]. Also Jungck [4] extended the results of Khan and Imdad [7] and proved common fixed point theorems for four mappings by using one of the mappings continuity and employing conditions of compatible mappings. Kang, Cho and Jungck [6] extended the results of Ding [1], Diviccaso and Sessa [2] and proved common fixed point theorems. Recently Sharma [11], Sharma and Patidar [15], Sharma and Deshpande [13, 14], Sharma and Choubey [12] have worked on this line. In 1993, Jungck, Murthy and Cho [5] introduced the concept of compatible mappings of type ( $\alpha$ ) in metric spaces. Now we begin with some definitions.

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**Definition 1.1:** Let (X, d) be a metric space.

- (1) A sequence  $\{x_n\}$  in a metric space (X, d) is said to be convergent to a point x in X, if  $\lim_{n\to\infty} d(x_n, x)=0$ .
- (2) A sequence  $\{x_n\}$  in a metric space (X , d) is said to be Cauchy sequence , if  $\lim_{m,n\to\infty} d(x_m$  ,  $x_n)=0$ .
- (3) A metric space (X, d) is said to be complete if every Cauchy sequence in X is convergent.

**Definition 1.2:** (Jungck [4]) Let A and B be mappings from a metric space (X, d) into itself. Then A and B are said to be compatible, if

 $\lim_{n\to\infty} d(ABx_n, BAx_n) = 0,$ where  $\{x_n\}$  is a sequence in x such that

 $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Bx_n = z$  for some  $z \in X$ .

**Definition 1.3:** (Jungck et al. [5]) Let A and B be mappings from a metric space (X, d) into itself. Then A and B are said to be compatible of type ( $\alpha$ ), if

$$\lim_{n\to\infty} d(ABx_n, BBx_n) = 0$$

and

 $\lim_{n\to\infty} d(BAx_n, AAx_n) = 0$ 

where  $\{x_n\}$  is a sequence in x such that

 $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Bx_n = z$  for some  $z \in X$ .

**Propostion 1.1:** (Jungck [4]) Let (X,d) be a metric space. Let A and B be continuous mappings from X into itself. Then A and B are compatible if and only if they are compatible of type  $(\alpha)$ .

**Propostion 1.2:** (Jungck et al. [5]) Let (X,d) be a metric space and A and B are mappings from X into itself. If A and B are compatible of type  $(\alpha)$  and Az = Bz for some  $z \in X$ , then

$$ABz = BBz = BAz = AAz$$
.

**Propostion 1.3:** (Jungck et al. [5] ) Let (X,d) be a metric space and A and B are mappings from X into itself. If A and B are compatible of type  $(\alpha)$  and  $\{x_n\}$  is a sequence in X such then

 $\lim_{n\to\infty} Ax_n = \lim_{n\to\infty} Bx_n = z$  for some  $z \in X$ , then

- (i)  $\lim_{n\to\infty} BAx_n = Az \text{ if } A \text{ is continuous at } z.$
- (ii) ABz = BAz and Az = Bz, if A and B are continuous at z.

#### **Implicit Relations:**

Let  $\Psi$  be the set of all real continuous functions  $\Phi(t_1, t_2, \dots, t_6) : R^{6_+} \to R$  satisfying the following conditions:

- $(\Phi_1)$   $\Phi(t_1, t_2, \ldots, t_6)$  is decreasing in the variables  $t_2, \ldots, t_6$ .
- $(\Phi_2)$  there exists  $h \in (0,1)$  such that for every  $u, v \ge 0$ ,
- $(\Phi_a): \Phi(u,v,v,u,0,u+v) \le 0 \text{ implies } u \le hv.$
- $(\Phi_b): \Phi(u,0,u,0,u,u) > 0 \ \forall \ u > 0, \ and$
- $(\Phi_c)$ :  $\Phi(u,0,0,u,0,u) > 0 \forall u > 0$ .

**Example 1.1:**  $\Phi(t_1, t_2, \dots, t_6) = t_1 - k \max\{t_2, t_3, t_4, \frac{1}{2}(t_5 + t_6)\}$  where  $k \in (0, 1)$   $(\Phi_1)$ : Obviously true.

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(\Phi_a): Let u > 0 then
\Phi(u,v,v,u,0,u+v) = u - k \max\{v,v,u,\frac{1}{2}(u+v)\} \le 0.
If u \ge v then u \le ku < u, a contraction. Thus u < v and u \le kv = hv, where h = k \in (0,1).
If u = 0, then u \le hv.
(\Phi_b): \Phi(u,0,u,0,u,u) = u - k \max\{0, u, 0, \frac{1}{2}(u+u)\}
                        = (1 - k) u > 0
                                            \forall u > 0.
(\Phi_c): \Phi(u_1,0_1,0_1,u_1,0_1,u) = u - k \max\{0,0,u,\frac{1}{2}(0+u)\}
                       = (1 - k) u > 0
                                               \forall u > 0.
Example 1.2: \Phi(t_1, t_2, \dots, t_6) = t_1^2 - t_1 (at_2 + bt_3 + ct_4) - dt_5 t_6
where a > 0, b.d \ge 0, 0 \le c < 1, a + b + c < 1 and b + d < 1.
(\Phi_1): Obviously holds.
(\Phi_a): Let u > 0 then
\Phi(u_1v_1v_2u_10_1u+v) = u^2 - u(av + bv + cu) - d.0 \le 0.
If u \le (a + b)/(1 - c) v = hv, where h = (a + b)/(1 - c) \le 1.
Therefore, u \le hv. If u = 0, then u \le hv.
(\Phi_b): \Phi(u_1,0,u_1,0,u_1,u) = u^2(1-(b+d)) > 0
                                                         \forall u > 0.
(\Phi_c): \Phi(u_10_10_1u_10_1u) = u^2(1-c) > 0
                                                       \forall u > 0.
Example 1.3: \Phi(t_1, t_2, \dots, t_6) = t_1 - k [\max \{ t_2^2, t_3 t_4, t_5 t_6, t_3 t_5, \frac{1}{2}, t_4 t_6 \}]^{\frac{1}{2}}
(\Phi_1): Obviously
(\Phi_a): Let u > 0 then
\Phi(u_1v_1v_2u_10_1u+v) = u - k [\max\{v^2, vu_1, 0, 0, \frac{1}{2}u(u+v)\}]^{\frac{1}{2}} \le 0.
If u \ge v then u \le ku < u, a contraction. Thus u < v and u \le kv = hv, where h = k \in (0,1).
If u = 0, then u \le hv.
(\Phi_b): \Phi(u,0,u,0,u,u) = (1-k)u > 0, \quad \forall u > 0.
(\Phi_c): \Phi(u,0,0,u,0,u) = (1-k/\sqrt{2})u > 0, \forall u > 0.
Popa [9] proved the following.
Theorem A: Let (X,d) be a complete metric space and A,B, S and T be mappings from X into itself
such that
               A(X) \subset T(X) and B(X) \subset S(X),
(i)
(ii)
               One of A,B, S and T mappings is continuous,
(iii)
               the pairs {A,S} and {B,T} are compatible,
              the inequality
(iv)
\Phi(d(Ax,By), d(Sx,Ty), d(Sx,Ax), d(Ty,By), d(Sx,By), d(Ty,Ax)) \le 0
for all x, y \in X and \Phi \in \Psi. Then A,B, S and T have a unique common fixed point in X.
We extend Theorem A for five mappings, moreover a different proof is given.
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**Theorem 1.1:** Let (X,d) be a complete metric space and A,B, S, T and P be mappings from X into itself such that

- (1.1)  $P(X) \subset AB(X)$  and  $P(X) \subset ST(X)$ ,
- (1.2) PB = BP, PT = TP, AB = BA, ST = TS,
- (1.3) A and B are continuous,
- (1.4) the pair  $\{P,AB\}$  is compatible of type  $(\alpha)$ ,
- (1.5)  $d(x,STx) \ge d(x,ABx)$ , for all  $x \in X$ ,

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(1.6)

the inequality

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\Phi(d(Px,Py), d(ABx,Px), d(ABx,STy), d(STy,Py), d(STy,Px), d(ABx,Py)) \le 0
for all x, y \in X and \Phi \in \Psi.
Then A, B, S, T and P have a unique common fixed point in X.
Proof: Let x_0 be an arbitrary point in X. Since P(X) \subset AB(X), we choose a point x_1 \in X such that Px_0 = X
ABx<sub>1</sub> and since P(X) \subset ST(X), for this a point x_1, there exists x_2 \in X such that Px_1 = STx_2. Inductively,
we can define a sequence \{y_n\} in X such that
y_{2n} = Px_{2n} = ABx_{2n+1} and
y_{2n+1} = Px_{2n+1} = STx_{2n+2}, n = 0,1,2,...
Letting x = x_{2n+1} and y = x_{2n+2} in (1.6), we write
\Phi(d(Px_{2n+1},Px_{2n+2}),\,d(ABx_{2n+1},Px_{2n+1}),\,d(ABx_{2n+1},STx_{2n+2}),\,d(STx_{2n+2},Px_{2n+2}),
d(STx_{2n+2},Px_{2n+1}), d(ABx_{2n+1},Px_{2n+2})) \le 0.
\Phi(d(y_{2n+1},y_{2n+2}),\ d(y_{2n},y_{2n+1}),\ d(y_{2n},y_{2n+1}),\ d(y_{2n+1},y_{2n+2}),\ d(y_{2n+1},y_{2n+1}),\ d(y_{2n},y_{2n+2})) \leq 0.
\Phi(d(y_{2n+1},y_{2n+2}),\ d(y_{2n},y_{2n+1}),\ d(y_{2n},y_{2n+1}),\ d(y_{2n+1},y_{2n+2}),\ 0,\ d(y_{2n},y_{2n+1})+d(y_{2n+1},y_{2n+2}))\leq 0.
By condition (\Phi_a), we have
(1.7) \quad d(y_{2n+1}, y_{2n+2}) \le h \ d(y_{2n}, y_{2n+1})
Similarly, by putting x = x_{2n} and y = x_{2n+1} in (1.6), we have
\Phi(d(Px_{2n},Px_{2n+1}),d(ABx_{2n},Px_{2n}),d(ABx_{2n},STx_{2n+1}),d(STx_{2n+1},Px_{2n+1}),
d(STx_{2n+1},Px_{2n}), d(ABx_{2n},Px_{2n+1})) \le 0.
\Phi(d(y_{2n},y_{2n+1}),\,d(y_{2n-1},y_{2n}),\,d(y_{2n-1},y_{2n}),\,d(y_{2n},y_{2n+1}),\,d(y_{2n},y_{2n}),\,d(y_{2n-1},y_{2n+1}))\leq 0.
\Phi(d(y_{2n},y_{2n+1}),d(y_{2n-1},y_{2n}),d(y_{2n-1},y_{2n}),d(y_{2n},y_{2n+1}),0,d(y_{2n-1},y_{2n})+d(y_{2n},y_{2n+1}))\leq 0.
By condition (\Phi_b), we have
(1.8) d(y_{2n}, y_{2n+1}) \le h d(y_{2n-1}, y_{2n})
Since h \in (0,1) it follows from (1.7) and (1.8) that \{y_n\} is a Cauchy sequence. Since X is complete, \{y_n\}
converges to a point z \in X. Since \{Px_{2n}\}, \{ABx_{2n+1}\} and \{STx_{2n+2}\} are subsequences of \{y_n\}, they also
converge to the point z, that is as
                                                n \to \infty, we have Px_{2n}, ABx_{2n+1} and STx_{2n+2} \to z.
Since A and B are continuous and the pair \{P, AB\} is compatible of type (\alpha) by proposition (1.3), we
have as n \to \infty
P(AB)x_{2n+1} = ABz \text{ and } (AB)^2x_{2n+1} = ABz.
Now we take x = ABx_{2n+1} and y = x_{2n+2} in (1.6), we write
\Phi(d(P(AB)x_{2n+1},Px_{2n+2}),d((AB)^2x_{2n+1},P(AB)x_{2n+1}),d((AB)^2x_{2n+1},STx_{2n+2}),
          d(STx_{2n+2},Px_{2n+2}),d(STx_{2n+2},P(AB)x_{2n+1}),d((AB)^2x_{2n+1},Px_{2n+2}))\leq 0.
Taking the limit n \to \infty, we have
\Phi(d(ABz, z), d(ABz, ABz), d(ABz, z), d(z, z), d(z, ABz), d(ABz, z)) \le 0.
\Phi(d(ABz,z),0,d(ABz,z),0,d(z,ABz),d(ABz,z)) \leq 0.
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which is a contradiction to  $(\Phi_b)$ . Thus ABz = z. Now by (1.5), since  $d(z,STz) \ge d(z,ABz) = 0$ , we also have STz=z. Therefore ABz = STz = z. Again by putting  $x = ABx_{2n+1}$  and y = z in (1.6), we write  $\Phi(d(P(AB)x_{2n+1},Pz),d((AB)^2x_{2n+1},P(AB)x_{2n+1}),d((AB)^2x_{2n+1},STz),$  $d(STz, Pz), d(STz, P(AB)x_{2n+1}), d((AB)^2x_{2n+1}, Pz)) \le 0.$ Taking the limit  $n \to \infty$ , we have  $\Phi(d(ABz, Pz), d(ABz, ABz), d(ABz, STz), d(STz, Pz), d(STz, ABz), d(ABz, Pz)) \le 0.$  $\Phi(d(ABz,PZz),0,0,d(ABz,Pz),0,d(ABz,Pz)) \leq 0.$ which is contradiction to  $(\Phi_c)$ . Thus ABz = Pz. Therefore ABz = STz = Pz = z. Now we show that Bz = z. On putting x = Bz and y = z in (1.6), we write  $\Phi(d(P(Bz), Pz), d(AB(Bz), P(Bz)), d(AB(Bz), STz), d(STz, Pz), d(STz, P(Bz)), d(AB(Bz), Pz)) \le 0$  $\Phi(d(Bz,z),d(Bz,Bz),d(Bz,z),d(z,z),d(z,Bz),d(Bz,z) \le 0,$  $\Phi(d(Bz,z),0,d(Bz,z),0,d(z,Bz),d(Bz,z) \le 0,$ a contradiction to  $(\Phi_b)$ . Thus Bz = z. Hence Az =z. Finally we show that Tz = z. By putting z = Tz and y = z in (1.6), we have  $\Phi(d(P(Tz), Pz), d(AB(Tz), P(Tz)), d(AB(Tz), STz), d(STz, Pz), d(STz, P(Tz)), d(AB(Tz), Pz)) \le 0$  $\Phi(d(Tz,z),d(Tz,Tz),d(Tz,z),d(z,z),d(z,Tz),d(Tz,z) \le 0$  $\Phi(d(Tz,z),0,d(Tz,z),0,d(z,Tz),d(Tz,z) \leq 0,$ a contradiction to  $(\Phi_b)$ . Thus Tz = z. Hence Sz = z. Combining the above results, we get Az = Bz = Sz = Tz = Pz = z. Thus z is a common point of A, B, S, T and P. For uniqueness let w  $(z \neq w)$  be another common fixed point of A, B, S, T and P. Then by (1.6), we write  $\Phi(d(Pz, Pw), d(ABz, Pz), d(ABz, STw), d(STw, Pw), d(STw, Pz), d(ABz, Pw)) \le 0$  $\Phi(d(z,w),d(z,z),d(z,w),d(w,w),d(w,z),d(z,w) \le 0,$  $\Phi(d(z,w),0,d(z,w),0,d(w,z),d(z,w) \leq 0,$ a contradiction to  $(\Phi_h)$ . Thus z = w. This completes the proof of the theorem.

**Remark 1.1**: In Theorem 1.1, if we replace the condition (1.5) by the following conditions (1.9) A, B, S and T are continuous,

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(1.10) the pairs {P, AB} and {P, ST}are compatible of type ( $\alpha$ ), then Theorem 1.1 is still true. By using Theorem 1.1, we have the following

**Theorem 1.2:** Let (X, d) be a complete metric space and A, B, S, T and  $\{P_a\}_{a\in A}$  be Mappings from X into itself such that the conditions (1.3) and (1.4) hold and

- (1.11)  $\bigcup_{a \in \Lambda} P_a(X) \subset AB(X)$  and  $\bigcup_{a \in \Lambda} P_a(X) \subset ST(X)$  where  $\Lambda$  is an index set,
- (1.12) for all  $a \in \Lambda$ ,  $P_aB = BP_a$ ,  $P_aT = TP_a$ , AB = BA, ST = TS,
- (1.13) for all  $a \in \Lambda$ , the pair  $\{P_a, AB\}$  is compatible of type  $(\alpha)$ ,
- (1.14) the inequality

$$\begin{split} &\Phi(d(P_ax,\,P_ay),\,d(ABx,\,P_ax),\,d(ABx,\,STy),\,d(STy,\,P_ay),\\ &d(STy,\,P_ax),\,d(ABx,\,P_ay)) \leq 0, \end{split}$$

for all  $x,y \in X$ ,  $a \in \Lambda$  and  $\Phi \in \Psi$ .

Then A, B, S, T and  $\{P_a\}_{a \in \Lambda}$  have a unique common fixed point in X.

Remark 1.2: In Theorem 1.2, if we replace the condition (1.5) by the condition (1.9) and the following condition

(1.15) for all  $a \in \Lambda$ , the pair  $\{P_a, AB\}$  and  $\{P_a, ST\}$  is compatible of type  $(\alpha)$ , then Theorem 1.2 is still true.

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